

USER MANUAL Fixturlaser EVO



Brand of ACOEM

EVO系列操作说明书



# CONTENT

Welcome to our world	1.1
Declaration of Conformity 合格声明	2.1
Safety 安全	3.1
Care 保养	4.1
Main Menu 主菜单	5.1
Shaft Alignment	6.1
Horizontal Machines 水平转轴对中	
Shaft Alignment	7.1
Vertical Machines 竖直转轴对中	
Machine Defined Data	8.1
Softcheck 软脚检查	9.1
Target Values 目标值预设	10.1
Tolerance Table 公差表	11.1
Memory Manager 存储器管理	12.1
Global Settings 全局设置	13.1
Display Unit EVO D 显示单元	14.1
Sensors M3 and S3 测量探头	15.1



## WELCOME TO OUR WORLD 简介

*Since the very beginning in 1984, ACOEM AB (formerly known as ELOS Fixturlaser AB) has helped industries throughout the world to achieve more profitable and sustainable production. We have reached where we are today by having the courage to think beyond the norm and follow slightly unconventional paths. We have had the courage to make mistakes and find new directions. Through our resolve, ambition and knowledge we have become a global player and a leader in innovative, user-friendly shaft alignment.*

### SUSTAINABLE INNOVATIONS

During our almost 30 years in this industry, we have explored, tweaked and tested more than anyone. Some might say we are incurable innovators whereas others might

say that we are highly focused. They both probably have a point. If we had not been devoted and ambitious, we would not have been the first in the industry to have a touch screen. Nor would we have been pioneers in the use of visible lasers and dual measurement heads.

Over the years, we have learnt to never compromise on quality and we are constantly in search of new, unexplored opportunities by combining advanced technology with design and function. By doing so, we have become the leading innovator in our industry. Not only do we minimize wear, production stoppages and costs, we also help save the environment. Natural resources are in short supply and if we can contribute to a more sustainable

world by making it a little bit straighter, we couldn't be happier.

## **TRUE COMMITMENT**

One reason for our success is our solid commitment. We have ensured that we remain attentive to constantly pick up on the needs of the market. Our expert employees and dedicated dealers in over 70 countries are undoubtedly our most important asset. Satisfaction and team spirit are of particular importance to us and are consistently at the top of our priority list. With experience from a wide range of industries and manufacturing processes, we are fully aware of the problems and needs of our end-customers. We are passionate about what we do and we are driven by the desire to eliminate anything in the industry

worldwide that may be even slightly out of line.

## **PURE USABILITY**

Our design and user-friendliness are carefully interwoven. As we develop new products, they also become cleaner, smarter, more functional and more robust. An industrial environment is demanding, infinitely more difficult to work in and inevitably subject to time pressure. There is no place for equipment with unnecessary functions, complicated interfaces and that is difficult to assemble.

Usability and user friendliness mean everything, not only to us but also to our customers. We have designed products that are easy to learn and can be incorporated quickly. By removing non-essential functions,

we make life less difficult for our users – and probably a little more difficult for our competitors.

## **END USER LICENSE AGREEMENT**

The rights to use the software in this product are offered only on the conditions that you agree to all the terms stated below, i.e. the end user agreement. By using this product you agree to be bound by this agreement. If you do not accept this agreement your sole remedy is to return the entire unused product, hardware and software, promptly to your place of purchase for a refund.

The user is granted a single license to use the software contained in this product. Use is only permitted on the hardware it has been installed on at the time of purchase. The software may not be removed from the hardware.

The software contained in the system is the property of ACOEM AB, any copying or redistribution is strictly prohibited.

Modifying, disassembling, reverse engineering or decompiling the system or any part thereof is strictly prohibited.

Disclaimer of warranties: To the maximum extent permitted by applicable law, ACOEM AB and its suppliers provide the software contained in this product 'as is' and with all faults, and hereby disclaim all other warranties either expressed, implied or statutory.

Limited liability: No liability shall exceed the price of the product, and the sole remedy, if any, to any claim shall be a right of return and refund.



ACOEM AB or its suppliers shall, to the maximum extent permitted by applicable law, not be liable to any indirect, special, incidental, punitive, and consequential damages arising from the use of the system or any part thereof, authorized or unauthorized.

ACOEM AB (formerly known as Elos Fixturlaser AB) is since mid-2014 a fully owned subsidiary of ACOEM Group, headquartered in Lyon, France. Other brands within ACOEM Group are 01dB, ONEPROD and METRAVIB. For more information please visit [www.acoemgroup.com](http://www.acoemgroup.com)



## **DECLARATION OF CONFORMITY** 合格声明

In accordance with the EMC Directive 2004/108/EC, the Low Voltage Directive 2006/95/EC, including amendments by the CE-marking Directive 93/68/EEC & EC directives RoHS 2011/65/EU.

### **Type of equipment**

Alignment System

### **Brand name or trade mark**

FIXTURLASER EVO

### **Type designation(s)/Model no(s)**

I-0935 FIXTURLASER EVO D

I-0913 FIXTURLASER M3

I-0914 FIXTURLASER S3

### **Manufacturer's name, address, telephone & fax no**

ACOEM AB

Box 7

SE-431 21 Mölndal

Sweden

Tel: +46 31 7062800

Fax: +46 31 7062850

The following standards and/or technical specifications, which comply with good engineering practice in safety matters in force within the EEA, have been applied:

### **Standard/Test report/Technical construction file/Normative document**

EN 61000-6-3:2007.

EN 61000-6-2:2005, EN 61000-4-2, -3, -4, -5, -6, -11.

EN 61010-1:2010

ISO9001:2008 Ref. No/ Issued by: DNV  
Certification AB Certification No. 2009-  
SKM-AQ-2704/2009-SKM-AE-1419.

The laser is classified in accordance with the  
International Standard IEC-60825-1:2014,  
USA FDA Standard 21 CFR, Ch 1, Part  
1040.10 and 1040.11 except for deviations  
pursuant to laser notice No. 50, dated June  
24, 2007.

The wireless device complies with Part 15 of  
the FCC Rules. Operation is subject to the  
following two conditions;

- (1) this device may not cause harmful  
interference, and
- (2) this device must accept any interference  
received, including interference that may  
cause undesired operation.

### **Additional information**

The product was CE-marked in 2014.

As manufacturer, we declare under our sole  
responsibility that the equipment follows the  
provisions of the Directives stated above.

### **Date and place of issue**

Möln dal 2014-03-11

### **Signature of authorized person**

A handwritten signature in black ink, appearing to read 'Hans Svensson', written over a horizontal line.

Hans Svensson, Managing Director

## SAFETY 安全

Retain and follow all product safety and operating instructions. Observe all warnings on the product and in the operating instructions.

请留意并遵循所有产品安全与操作指导。  
注意所有警示说明。

Failure to observe the safety pre-cautions and operating instructions can cause bodily injury, fire, and damage to the equipment. 忽略不循序安全警告语操作说明有可能导致受伤，火灾与仪器损坏。

Do not disassemble, modify or use the equipment in other ways than explained in the operating instructions. ACOEM AB will not accept any liability for such use.

请勿拆开，维修或用不当的方式使用设备。  
否则Fixturlaser.不承担相关责任。



## WARNING! 警告

Do not mount equipment on running machines and take all appropriate measures to prevent unintentional start-up of machines. Make sure to fully comply with all appropriate shut down procedures, safety measures and regulations at worksite and local regulations regarding safety in a machine environment.

请勿在运转设备上安装仪器并防止设备意外开启。请确认完全遵循当地关机程序，安全操作规则。

## LASER PRECAUTIONS 激光防护

FIXTURLASER EVO uses laser diodes with a power output of  $< 1.0$  mW. The laser classification is Class 2.

FIXTURLASER.EVO使用二级半导体激光，输出功率小于1毫瓦

Class 2 is considered safe for its intended use with only minor precautions required.

These are: 二级激光要求：

- Never stare directly into the las 请勿直视激光发射器
- Never shine the laser directly into anyone else's eyes. 请勿将激光照射到他人眼睛



COMPLIES WITH 21 CFR 1040.10 AND 1040.11  
EXCEPT FOR DEVIATIONS PURSUANT TO  
LASER NOTICE No. 50, DATED JUNE 24, 2007



### CAUTION!

USE OF CONTROLS OR ADJUSTMENTS OR PERFORMANCE OF PROCEDURES OTHER THAN THOSE SPECIFIED HEREIN MAY RESULT IN HAZARDOUS RADIATION EXPOSURE.

使用其它的控制装置有可能导致设备损坏或人身伤害

Your system complies with the requirements in:

- IEC-60825-1:2007
- British Standard BS EN 60825-1
- DIN EN 60825-1

USA FDA Standard 21 CFR, Ch I, Part 1040.10 and 1040.11

## POWER SUPPLY 电源

FIXTURLASER EVO is powered by a high-capacity rechargeable Li-Ion battery mounted in the display unit or by the external power unit. EVO电显示单元内置高能锂电池供电，也可以外部交流供电。



Both the display unit and the measurement units (M3 and S3) can be connected to the charger and charged while lying in the case. It is important that the lid of the case is open during the charging or else the system will not be charged properly and might be damaged.

显示单元与激光探头可以在箱内同时充电，充电时请注意不要关闭箱盖，否则有可能损坏充电器。

Do not expose the power adapter to rain, or wet conditions.

电源适配器不要暴露于潮湿环境中

Always unplug the charger from the electrical outlet after charging.  
充电之后及时从插座上拔掉充电器

Leaving a display unit or a measurement unit with an empty battery for a prolonged time can reduce the capacity of the battery or even damage the battery.

让主机或探头的电池长时间处于空电状态会降低电池容量甚至损坏电池

If the system is not used for a long time, charge the batteries to approximately 50-75% before storing the system, if kept in storage repeat this every 3-4 month (if needed)  
如果仪器长时间不用的话，在存放之前请将仪器电池电量保持在50%-75%之间，并且每隔3-4个月重复一次。



When used in typical conditions the battery will sustain good capacity for approximately 2-3 years before needing replacement.

Contact your sales representative for battery replacement.

通常情况下使用电池可以维持2-3年，如需更换电池请联系当地供应商。

The batteries contain safety circuitry to operate safely with the display unit. The unit can therefore only be used with the Li-Ion batteries supplied by FIXTURLASER.

电池包含安全电路以保证显示单元操作安全，请勿使用非Fixturlaser提供的锂电池。

Improper replacement of batteries can cause damage and risk for personal injury.

不正确的电池更换可能导致人身伤害



## **WARNING!**

**BATTERY REPLACEMENT SHALL ONLY BE PERFORMED BY AUTHORIZED FIXTURLASER REPRESENTATIVES.**

电池更换必须由Fixturlaser授权经销商进行

**USE OF ANY OTHER BATTERIES THAN THOSE SUPPLIED BY FIXTURLASER WILL CAUSE SEVERE DAMAGE TO THE DISPLAY UNIT AND CAN CAUSE RISK FOR PERSONAL INJURY!**

使用非Fixturlaser提供的其他品牌电池有可能导致显示单元损坏并有可能引起人身伤害。

Handle any batteries with care. Batteries pose a burn hazard if handled improperly. Do not disassemble and keep away from heat sources. Handle damaged or leaking batteries with extreme care. Please keep in mind that batteries can harm the environment. Dispose of batteries in accordance with local regulatory guidelines, if in doubt contact your local sales representative.

小心操作电池，不正确的操作可能导致电池烧毁。请勿拆解电池，并请远离火源。

Only use the external power adapter supplied by FIXTURLASER for use with the Display Unit. Using other power adapters can cause damage to the unit and personal injury.

请勿使用其他品牌电源适配器充电。

## WIRELESS TRANSCEIVER

The FIXTURLASER EVO system is fitted with a Bluetooth wireless transceiver.

.EVO系列的系统内置蓝牙传输装置。

Make sure that there are no restrictions on the use of radio transceivers at the site of operation before using the wireless transceivers.

使用时请先确保当地关于无线电发射装置的限制规定

Please refer to the chapter “Global settings” on how to turn off the Bluetooth transmitters for use in restricted environments.

在显示使用区域，请参考“全局设定”章节关闭蓝牙传输。



## WARNING!

Before using the wireless transceivers make sure that there are no restrictions on the use of radio transceivers at the site. Do not use on aircraft.

使用时请先确保当地关于无线电发射装置的限制规定。请勿在航空器上使用。



## CARE 保养

### PACKING THE CASE 仪器箱



### PACKING POWER SUPPLY 电源适配器



Both the display unit and the measurement units (M3 and S3) can be connected to the charger and charged while lying in the case. The power supply has to be placed in the case as in picture and the lid of the case has to be open during the charging or else the system might be overheated.

显示单元与激光探头可以在箱内同时充电，充电时请注意不要关闭箱盖，否则有可能损坏充电器。

## CLEANING 清洁

The system should be cleaned with a cotton cloth or a cotton bud moistened with a mild soap solution, with the exception of the detector and laser window surfaces, which should be cleaned with alcohol.

请使用湿棉布或棉签擦拭系统。激光接收器  
请使用酒精擦拭。



For the best possible function, the laser diode apertures, detector surfaces and connector terminals should be kept free from grease or dirt. The display unit should be kept clean and the screen surface protected from scratches.

请保持激光二极管缝隙，接收器表面，连接线清洁，无油污。显示单元应预防刮伤。



Do not use paper tissue, which can scratch the detector surface.

请勿使用抽纸，会导致接收器刮伤。



Do not use acetone. 请勿使用丙酮

The chains on the V-block fixtures are delivered dry. If the system is used in highly corrosive environments, the chains should be oiled.

新出厂的V.型夹具的链条是干燥的。如果在高腐蚀性环境中使用，应给链条上油。

## DATE OF CALIBRATION

### DISCREPANCY 标定日期差异

Our instruments store the electronic date of the latest calibration of the instrument. Due to production processes and storage time, this date will differ from the date of the calibration certificate. Hence, it is the date of the calibration certificate which is important and that indicates when the next calibration is due.

我们的仪器内记录有最新标定的日期。因为生产与仓储原因，此日期会与标定证书日期略有差异。请以标定证书日期为准。





## MAIN MENU 主菜单

The FIXTURLASER EVO is provided with different programs for specific purposes.  
FIXTURLASER EVO根据您的需要提供不同的程序。



Press the ON button to start the system  
and the Main Menu appears.  
按下电源启动按钮启动系统，主菜单会显示。



In the Main Menu you can select the  
program that you want to use.  
在主菜单里您可以选择想要的程序

In the Main Menu you will also find the  
Memory Manager and Global Settings.  
在主菜单中您可以找到内存管理与环境设定。

## APPLICATION PROGRAMS



Shaft Alignment Horizontal  
Machines

水平转轴对中



Shaft Alignment Vertical Machines  
垂直转轴对中



Machine Defined Data  
定义设备数据

## MEMORY MANAGER



Memory Manager  
存储管理

## SYSTEM FUNCTIONS



Global Settings  
参数设置



Off  
关机



Wireless indicator  
蓝牙图标



Battery indicator  
电源显示

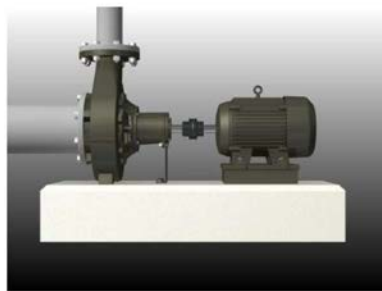
## SHAFT ALIGNMENT HORIZONTAL MACHINES

### 水平转轴对中

#### INTRODUCTION 简介

Shaft alignment: Determine and adjust the relative position of two machines that are connected, such as a motor and a pump, so that the rotational centers of the shafts are collinear, when the machines are working in a normal operating condition. Correction of horizontal shaft alignment is done by moving the front and the rear pair of one machine's feet, vertically and horizontally, until the shafts are aligned within the given tolerances. A tolerance table is available in the system.

轴对中：测定和调整两台连接设备，使其旋转中心共线。水平对中的调整是通过调整设备前后脚的高低和水平位移，使其达到公差允许值。



The FIXTURLASER EVO system has two measuring units that are placed on each shaft by using the fixtures supplied with the system.

FIXTURLASER的对中系统有两个测量单元，分别用夹具安装在联轴器两端的轴上

。



After rotating the shafts into different measuring positions the system calculates the relative distance between the two shafts in two planes. The distances between the two measuring planes, distance to the coupling and distances to the machine feet are entered into the system. The display box then shows the actual alignment condition together with the position of the feet.

Adjustment of the machine can be made directly, according to the displayed values.

The alignment results can be saved in the memory manager. The measurements in the memory manager can easily be transferred to a PC for further documentation purposes.

动测量轴到不同位置，系统会计算两轴的相对位移，并显示对中结果和调整建议。角度偏差调整需增减垫片，位移偏差需侧向移动。

.测量结果可保存在文件存储器里，并且可以传送到电脑转换成文档格式。

## PRE-ALIGNMENT FUNCTIONS

### 预对中功能

In an effort to obtain the best possible conditions for shaft alignment, it is necessary to perform some pre-alignment checks. In many cases it is necessary to make these checks in order to obtain precise alignment. It is often impossible to reach the desired alignment results if you do not make any pre-alignment checks. 为获得最佳的对中效果需在测量之前做一些检查工作以保证获得精确测量数据。

Before going on site, check the following:  
去现场之前，请检查下列要求：

What are the required tolerances? 测量公差?

Any offsets for dynamic movements? 动态位移补偿?

Are there any restrictions for mounting  
the measuring system?

装条件是否受限？

Is it possible to rotate the shaft?

测量轴是否可旋转？

What shim size is needed?

所需垫片尺寸？

Before setting up the alignment system on the machine, check the machine foundation, bolt and shim condition. Also check if there are any restrictions in adjusting the machine (if e.g. there is enough space to move the machine).

安装对中系统之前请检查设备底座，螺丝与垫片情况以及是否有空间限制

After the visual checks have been performed, there are some conditions that have to be considered:

目测检查完成后，考虑以下情况:

Check that the machine has the right temperature for alignment.  
设备温度是否正常?

Take away old rusty shims (check that you can remove shims).  
移除旧的生锈垫片?

Check coupling assembly and loosen the coupling bolts.  
检查联轴器连接情况，松开联轴器螺丝?

Check soft foot conditions.  
检查软脚情况

Check coupling and shaft run-out. 检查联轴器与转轴离合情况

- Pipe work strain. 管道张力
- Coarse alignment. 粗对中
- Check coupling gap (axial alignment). 检查耦合间隙

Mechanical looseness.  
设备有无负载?

## MOUNTING 安装

The sensor marked “M” should be mounted on the movable machine and the sensor marked “S” on the stationary machine. The sensors shall be assembled on their V-block fixture, and placed on each side of the coupling.

Hold the V-block fixture upright and mount it on the shafts of the measurement object. 有M.的单元装在可动设备端，有S.的装在固定端。用V.型夹具固定



Lift the open end of the chain, tension it so that the slack is removed and attach it to the hook.

将V.型夹具向上安装在轴上，用锁紧链条固定。



Firmly tighten the chain with the tensioning screw. If necessary, use the supplied tensioning tool. Do not over-tighten. If the shaft diameter is too large the chains can be extended with extension chains.

将用提供的扳手锁紧螺丝，不要过紧。如轴径过大，需使用延长链条。（可选）



Adjust the height of the sensor by sliding it on the posts until a line of sight is obtained for both lasers. Secure its position by locking both clamping devices on the back of both units

调整激光器高度直到两侧的激光都可以接收，锁紧两侧的夹子使其固定。





The laser of the M-sensor can be adjusted with the adjustment screw on the top of the unit. There is normally no need to adjust the laser, but this might be necessary when measuring at long distances.

**NOTE:** Make sure that the adjustment screw is secured with the locking nut after adjustment.

在M.激光发射器顶端有一个微调螺丝，可以调整M.激光器发射激光的高低位置。不过除了长距离的测量外，通常没有必要调整激光。

注意：请在调整前后锁紧固定螺母

## STARTING THE PROGRAM 开始程序



Start the program by touching the Horizontal Shaft Alignment icon in the Main Menu. 在主菜单选择水平对中程序



Go to Settings for selecting measurement method and other settings. 进入设置选项选择公差值及其它设定

## SETTINGS 设置



These settings are unique for this application. 设定只对本次测量有效

For most of the settings, the current selection is shown in the icon.

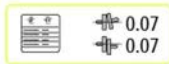
### Sampling time 采样时间



Opens window for selection of sampling time. Select normal or long sampling time. Long sampling time is suitable for high vibration environments.

可选一般采样时间或延长采样时间，延长时间适用于现场振动大的测量环境

### Tolerance table 公差表



Opens the tolerance table. See chapter “Tolerance table”.

打开公差表根据需求选择公差值

### Coupling gap

联轴器间隙



Opens window for entering of coupling diameter.

点击输入联轴器直径

## Adjustable screen filter 抗干扰调整



Opens window for activating or deactivating the adjustable screen filter. 点击开启或关闭干扰调整

Note: The adjustable screen filter should be deactivated for normal operation, and only activated in environments with severe vibrations. 注意：该选项开启适用于严峻的振动测量环境。

## Screen flip 视角显示



Opens window for selection of selection of screen flip. Select normal screen or screen flip. 点击选择正常视角或者相反位置

## Target values 目标值



Opens Target values. See chapter “Target values”. 点击输入目标补偿值

## Turn off inclinometers 关闭倾角仪

If the inclinometers are not functioning properly, e.g. in high vibrations, they can be disabled. 倾角仪在高振动环境中不正常显示，可关闭



Turns off the inclinometers.

Measurement with disabled inclinometers is described in the end of this chapter.

无倾角仪的测量在本章结尾处说明

## **Add new machine with defined data** 添加新设备的定义参数



Opens window for adding a new machine with defined data to Machine Defined Data. 打开窗口添加新的设备以及设定好参数

Entered data such as distances, Target values and tolerances, will be saved. 输入数据比如对中距离，目标值和公差值，保存后将应用于新的设备

## **Confirm** 确认



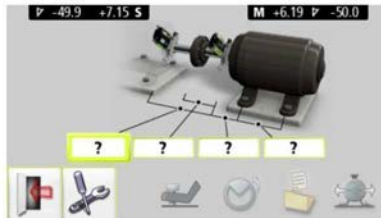
Exits the Settings and returns to the application. 退出设定界面返回程序

## ENTER DIMENSION 输入参数

The screen displays the movable machine.

图示可动端设备

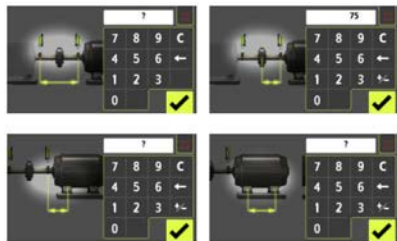
The traffic lights show green when the laser hits the detector. 绿色指示灯表示探头接受激光正常



Select the dimension boxes to enter dimensions. 选择尺寸框输入尺寸

Measure and enter dimensions and tolerance.

测量与尺寸输入



You must enter all the distances. The distance between the sensors, the distance between the centre of the coupling and the M-sensor, the distance between the M-sensor and the first pair of feet and the distance between the first and the second pairs of feet.

必须输入两激光器间距，M.激光器到联轴器中心距，M.激光器到设备前脚距离与设备前后脚距离。

## **SOFTCHECK.**软脚检查



Go to Softcheck for checking soft foot conditions.

See chapter “Softcheck”.  
点击进入软脚检查界面。

## **TARGET VALUES .**目标值



Go to Target Values for entering target values.

See chapter “Target Values”.  
点击进入目标值预设界面

## MEASUREMENT METHOD 测量方法



### Tripoint™ method 三点法

In the Tripoint method, the alignment condition can be calculated by taking three points while rotating the shaft at least 90°. 三点法需要测量三个位置，每个位置点距离至少90.度。

**NOTE:** The shafts should be coupled during measurement in order to achieve as reliable and accurate results as possible, when using the Tripoint method.

注意：当使用三点法测量时，为了达到尽可能可信和精确的测量结果，转轴连轴器需要连接

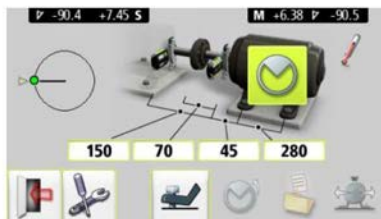
**TIP:** The larger the angle over which the three points are measured, the fewer moves and repeat measurements will have to be made. Minimum angle between readings is 45°. 提示：所测三点距离角度越大，重复性越好。两次测量之间的最小角度为45.度



A green flashing arrow suggests suitable measurement positions.  
闪烁的绿色箭头显示合适的测量位置。



## MEASUREMENT POINT REGISTRATION 测量点记录



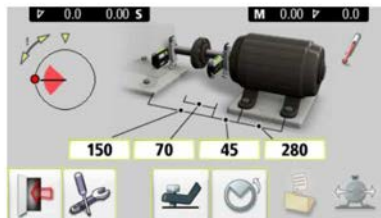
Set the sensors at approximately the same rotational angle at the first measurement position. 第一个测量位置，将激光器调整至大约相同位置



Touch the register icon.

点击记录按钮

This registers the first reading.  
测量并记录第一个位置读数



Rotate the shafts to the next position. The shafts must be rotated over a minimum of 45°.

转动测量轴到下一个测量位置。轴的转动最小角度必须大于45度。

Green sector show permitted positions.  
Red sector show forbidden positions. The Register icon is not shown if the rotation is less than 45°.

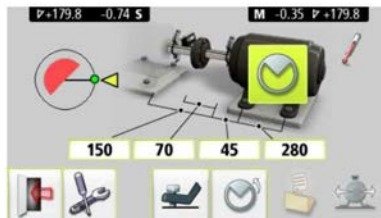
绿色区域表示可测区域，红色为非可测区域。  
当转动角度小于45度时测量图标不显示。



Touch the register icon.

This registers the second reading.

点击记录按钮记录第二个测量点



Touch the register icon.

This registers the third reading.

点击记录按钮记录第三个测量点

Rotate the shafts to the third position.  
转动测量轴至第三个测量位置

TIP: When registering the third reading at the 3 o'clock position, the sensors will already be in the right position for horizontal alignment.

## MEASUREMENT RESULTS



The Measurement Result screen shows coupling values and foot values in both the vertical and horizontal direction.

The symbol to the left of the coupling values indicates the angular direction and offset, and also if the values are within tolerance. 测量结果同时显示水平垂直方向的对中值与调整值。左侧的符号表示位移偏差与角度偏差，以及是否在公差范围内。



Within tolerance (green).  
绿色表示在公差范围内



Within double tolerance (yellow and inverted).

橙色表示在两倍公差内



Out of double tolerance (red and inverted). 红色表示超出两倍公差



When a coupling is in tolerance in one direction, this is indicated with a check symbol at the motor.

当联轴器在一个方向的测量结果在公差内，显示此图标

The machine picture itself also indicates the coupling alignment. 设备的图片本身也可以显示对中结果的好坏



Save the measurement result. 保存测量结果



Go to shimming 作调整

## EVALUATING THE RESULT

### 测量结果评估

The angle and offset values are used to determine the alignment quality. These values are compared with the alignment tolerances to determine whether correction is necessary. If suitable tolerances are selected in the tolerance table, the symbols described above indicate if the angle and offset values are within tolerance or not. The foot values indicate the movable machine's foot positions where corrections can be made.

角度偏差与位移偏差可以衡量对中情况，并计地脚是否需要进行调整。如果已经选择合适的公差，测量结果会通过不同颜色表示是否在公差范围之内。地脚调整值给出设备对中需要进行的地脚调整数据。

Depending on the result, the program will also guide the user. First, the program will always recommend the user to save the measurement. 基于对中结果，程序会一直指导用户。首先程序会建议用户保存测量数据。

Then, if the measurement result shows that the machine is misaligned, the user will be recommended to go to shimming.

之后，如果测量结果显示设备存在不对中，程序会建议用户进行调整

If the measurement result is within tolerance and has been saved, the system will recommend the user to exit the measurement. 如果测量结果是在公差范围之内并且已经被保存则系统会建议用户退出程序。

## SHIMMING 调整



The Shimming screen shows foot values in the vertical direction as suitable shim values (0.05 mm / 1 mil). 垫片界面显示竖直方向地脚调整值

The arrows show if shims must be added or removed to adjust the machine in the vertical direction. 箭头表示加或者减垫片

The check signs show that shimming is not needed. 对勾图标表示无需更改垫片厚度

When shimming is completed, continue to alignment for adjustments in the horizontal direction. 垫片加减完成后，继续进行水平方向调整



Go to alignment.  
进入对中

## ALIGNMENT 对中

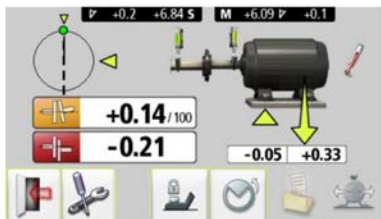
If the machine has been adjusted vertically in the shimming screen, go directly to alignment in the horizontal direction.

如竖直方向已完成调整，直接进入水平方向调整

If the machine has not been adjusted in the shimming screen, alignment in the vertical direction has to be done first.

如未在垫片界面进行调整，此时可在对中界面先进行竖直方向调整。

### Vertical.direction.

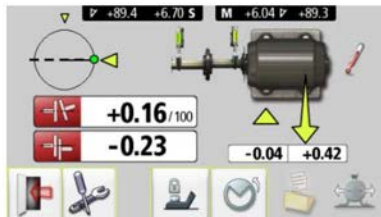


Rotate the shafts to the 12 or 6 o'clock position to make adjustments in the vertical direction. The angle guide helps you to reach the right position. 旋转主轴至.12.点或.6.点钟方向调整竖直方向对中，倾角仪帮您达到正确的位置。

Adjust the machine vertically until the values for both angular and parallel alignment are within tolerance. The arrows by the feet show in which direction the machine should be moved.

在竖直方向调整设备直到角度与位移同时达到公差范围内。黄色箭头表示需要调整的方向。

## Horizontal direction



Rotate the shafts to the 3 or 9 o'clock position to make adjustments in the horizontal direction. The angle guide helps you to reach the right position.

旋转主轴到.3.点或.9.点钟方向调整水平对中。Adjust the machine horizontally until the values for both angular and parallel alignment are within tolerance. The arrows by the feet show in which direction the machine should be moved. 在水平方向调整设备直到角度与位移都达到公差范围内。黄色箭头表示需要调整的方向。

## Check and re-measure 检查与重新测量

Rotate the shafts back to the 12 or 6 o'clock position and check that the machine is still within tolerance.

主轴转回12.点或.6.点钟方向，检查测量结果是否发生变化。

Alignment is now completed. To confirm the result, re-do the measurement.  
Re-measure.



对中调整完成，为确保对中结果，可以重新测量。

## FEET LOCK FUNCTION 地脚锁定功能

In some cases the machine that is displayed as the movable machine is not movable, or maybe some of the feet are not adjustable. In order to perform proper alignment in these cases, the Feet Lock function can be used. This function allows you to select which feet are locked and which feet are adjustable.

在某些情况下，调整端不可移动或受限。为了达到合适的对中调整，需要地脚锁定功能。此功能允许选择需锁定的地脚与可调整地脚。

Feet Lock is available both in shimming and alignment.

Touch the Feet Lock icon to enter the Feet Lock function.

点击地脚锁定按钮进入



Enter dimensions. The required distances are those between the first and second pairs of feet on the stationary machine and between the first pair of feet on the stationary machine and the first pair of feet on the movable machine.

输入静止端设备前后地脚的距离，同时输入静止端设备与可动端设备前脚之间的距离。



Select the two pairs of feet you want to lock.

选择需要锁定的一组地脚



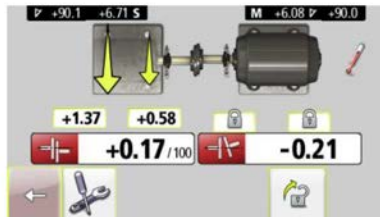
## Feet Lock Shimming 高低方向锁定



Shim values are shown for the two pairs of feet that are not locked.

未锁定的一组地脚所需加减垫片量显示出来

## Feet Lock Alignment 水平对中方向锁定



Live values are shown for the two pairs of feet that are not locked.

此时数据实时显示未锁定地脚的调整值。

## SCREEN FLIP视角切换



Screen Flip enables the user to see the machine set-up from the actual view.  
视角切换功能能够让用户看到设备的真实相对位置

Select screen flip in settings. 在设置界面里面选择视角切换功能



## OTHER FEATURES 其他特性

### Looseness indicator 松动标识

The system has a function for detecting coupling backlash and looseness in order to achieve optimum accuracy. The system will display the looseness indicator if one of the following conditions is met: 系统通过此功能监测联轴器间隙与松动，以达到优化的精度。如下列情况之一发生则松动标识出现：

- The M and S units are more than  $3^\circ$  apart. 两激光单元角度差大于3度
- The mutual angular position changes more than  $0.7^\circ$  from that when the first measurement point was taken.

第一点测量完成后两激光器同步角度大于0.7度

When the coupling backlash or looseness is eliminated to avoid any of the above conditions, the looseness indicator will automatically disappear. 联轴器间隙与松动消除之后，此图标自动消失

### Target Value symbol 目标值预设



When Target Values are used in the measurement, this is indicated with the Target Value symbol in the upper right corner of the screen.

设的目标值后，此图标会显示

### Coupling gap 联轴器间隙



The result can be presented as a coupling gap. 结果可表示成联轴器间隙

Coupling diameter can be entered in settings. 联轴节直径在设置界面中输入

## Measurement with disabled inclinometers 关闭倾角功能测量

If the inclinometers are not functioning properly, e.g. in high vibrations, they can be disabled.当倾角仪在高振动环境下显示不正常时可关闭倾角仪功能

- Turn off the inclinometers in Settings.  
关闭倾角仪

When the inclinometers are disabled the system will work as normal with the following exceptions: 关闭倾角仪之后正常测量按以下步骤操作：.

- The readings have to be registered according to the "clock method". Register the first reading at 9 o'clock, rotate the shafts 180° and register the second reading at 3 o'clock, rotate

90° back to 12 o'clock to register the third and final reading.

根据锁定模式依次将轴转动到9点钟，3点钟，12点钟三个方向，并记录在这3个方向上测量到的数据。

- During alignment, use the change view icon to change from horizontal to vertical view of the machine and vice versa. 对中过程可以切换水平与竖直方向的视图来观察设备的实时对中情况，通过转动轴至9点钟或者12点钟方向实现



NOTE: When disabling the inclinometers they will remain disabled until leaving the Shaft Alignment application for the Main Menu.

注意：当关闭倾角仪后，会有倾角数据滞留在对中程序的界面上。

## SHAFT ALIGNMENT 立式转轴对中 VERTICAL MACHINES

### INTRODUCTION简介

Shaft alignment: Determine and adjust the relative position of two machines that are connected, such as a motor and a pump, so that the rotational centers of the shafts are collinear, when the machines are working at a normal operating temperature. Correction of vertical shaft alignment is done by moving the flange of the machine until the shafts are aligned within given tolerances. A tolerance table is available in the system.

轴对中：测定和调整两台连接设备，使其旋转中心共线。水平对中的调整是通过调整设备前后脚的高低和水平位移，使其达到公差允许值



The FIXTURLASER system has two measuring units that are placed on each shaft by using the fixtures supplied with the system.

FIXTURLASER的对中系统有两个测量单元，分别用夹具安装在联轴器两端的轴上



After rotating the shafts to different measuring positions, the system calculates the relative distance between the two shafts in two planes. The distances between the two measuring planes, distance to the coupling, number of bolts and pitch circle diameter are entered into the system. The display box then shows the actual alignment condition together with the position of the feet. Adjustment of the machine can be

made according to the values displayed. The angular misalignment is corrected by placing shims under the bolts and offset is corrected by moving them laterally.

The alignment results can be saved in the memory manager. The measurements in the memory manager can easily be transferred to a PC for further documentation purposes.

转动测量轴到不同位置，系统会计算两轴的相对位移，并显示对中结果和调整建议。角度偏差调整需增减垫片，位移偏差需侧向移动。

测量结果可保存在文件存储器里，并且可以传送到电脑转换成文档格式。

## PRE-ALIGNMENT FUNCTIONS 预对中功能

In an effort to obtain the best possible conditions for shaft alignment, it is necessary to perform some pre-alignment checks. In many cases it is necessary to make these checks in order to obtain precise alignment. It is often impossible to reach the desired alignment results if you do not make any pre-alignment checks. 为获得最佳的对中效果，需在测量之前做一些检查工作以保证获得精确测量数据。

Before going on site, check the following:

What are the required tolerances? 公差要求

Any offsets for dynamic movements? 是否带有动态补偿

Are there any restrictions for mounting the measuring system? 安装条件是否受限

Is it possible to rotate the shafts? 轴是否可旋转

What shim size is needed? 所需垫片类型

Before setting up the alignment system on the machine, check the machine foundation, bolt and shim conditions. Also check if there are any restrictions in adjusting the machine (if e.g. there is enough space to move the machine). 安装对中系统之前请检查设备底座，螺丝与垫片情况以及是否有空间限制

After the visual checks have been performed, there are some conditions that have to be considered: 目测检查后，考虑以下情况

- Check that the machine has the right temperature for alignment? 设备温度是否正常
- Take away old rusty shims (check that you can remove shims). 移除生锈垫片
- Check coupling assembly and loosen the coupling bolts. 检查联轴器连接情况  
松开连接螺栓
- Check soft foot conditions. 检查软脚情况

- Mechanical looseness..机械松动
- Check coupling and shaft run-out.  
检查联轴器与轴的磨损情况
- Pipe work strain. 管道应力
- Coarse alignment. 粗调整
- Check coupling gap (axial alignment).

检查联轴器间隙

## **MOUNTING .安装**

The sensors are mounted as described in chapter “Shaft Alignment Horizontal Machines”. 激光器安装参考“卧式轴对中”章节



## STARTING THE PROGRAM开始程序

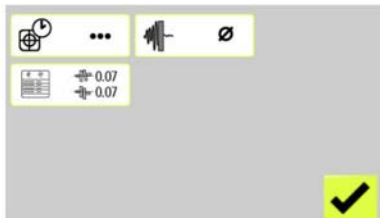


Start the program by touching the Vertical Shaft Alignment icon in the Main Menu. 点击立式对中图标开始



Go to Settings for selecting measurement method and other settings. 进入测量方法设置

## SETTINGS 设定



These settings are unique for this application. 设定只对此应用有效

For most of the settings, the current selection is shown in the icon. 大部分的应用设置会显示在图标中

## Sampling time 采样时间



Opens window for selection of sampling time. Select normal or long sampling time.

Long sampling time is suitable for high vibration environments.

选一般采样时间或延长采样时间，延长时间适用于现场振动大的测量环境

## Tolerance table 公差表



Opens the tolerance table. See chapter "Tolerance table". 打开公差表根据需求选择公差值.

## Adjustable screen filter 抗干扰调整



Opens window for activating or deactivating the adjustable screen filter. 点击开启或关闭干扰调整.

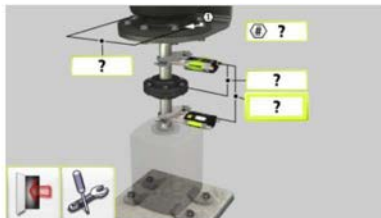
Note: The adjustable screen filter should be deactivated for normal operation, and only activated in environments with severe vibrations. 注意：该选项开启适用于严峻的振动测量环境.

## Confirm 确认



Exits the Settings and returns to the application.  
退出设定界面返回程序

## ENTER DIMENSIONS 输入尺寸



The screen displays the movable machine.  
The traffic lights show green when the laser hits the detector. 图示可动端设备。当激光照射到探头接收窗口时显示指示灯显绿色。

Select the dimension boxes to enter dimensions.  
选择尺寸对话框输入尺寸

Measure and enter dimensions and tolerance. 测量与尺寸输入以及选择公差值

You must enter all the distances. The distance between the sensors, the distance between the centre of the coupling and the M-sensor, and the pitch circle diameter and the number of bolts.

必须输入所有测量距离，包括两激光器间距，M.激光器到连轴器中心距，输入节距圆直径与总螺栓数

Up to 8 bolts can be entered.

最多可测输入8.个螺栓

## MEASUREMENT METHOD 测量方法

In the Vertical Shaft Alignment program, machinery positions are calculated by taking three points with 180° of rotation.

在竖直轴对中程序要求轴旋转180.度，取三点读数

## MEASUREMENT POINT REGISTRATION 测量点记录



Place yourself at the position corresponding to the second measurement position, where it is easiest to turn the shafts through 180°. 站在第二测量点位置，此位置需方便将轴旋转180度

The first measurement position has to be at bolt number 1. 第一个测量点必须在第一个螺栓位置开始

Tip: Mark the positions 1, 2 and 3 before you start measuring.

提醒：开始测量前标出1, 2, 3点的位置



Set the sensors at approximately the same rotational angle at the first measurement position, with bolt number 1 to the right. 第一个测量位置，将激光器调整至第一个螺栓大约相同位置



Touch the register icon. 点击测量图标

This registers the first reading.

记录第一个测量数据

Rotate the shafts 90° to the second position  
(where you are standing).

旋转90.度到第二测点（您所站位置）



Touch the register icon.

This registers the second  
reading.

选择测量图标点击，记录第二个测量点

Rotate the shafts 90° to the third position,  
to the left.

旋转90.度到第三点位置

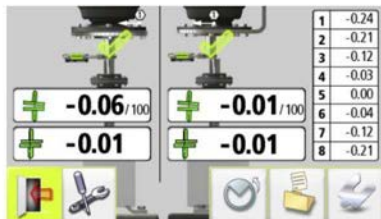


Touch the register icon.

This registers the third  
reading.

选择测量图标点击，记录第三个测量点

## MEASUREMENT RESULTS



The Measurement Result screen shows coupling values in both directions, and bolt values. 测量结果同时显示两个方向的对中值与调整值

The symbol to the left of the coupling values indicates the angular direction and offset, and also if the values are within tolerance. 左侧的符号表示位移偏差与角度偏差，以及是否在公差范围内



Within tolerance (green).  
绿色表示在公差内



Within double tolerance (yellow and inverted).  
黄色表示在两倍公差内



Out of double tolerance (red and inverted).  
红色表示超两倍公差



When a coupling is in tolerance in one direction, this is indicated with a check symbol at the motor.

当联轴器在一个方向的测量结果在公差内会显示此图标



Save the measurement result.  
保存测量结果



Go to shimming 做出调整

## **EVALUATING THE RESULT** 测量结果评估

The angle and offset values are used to determine the alignment quality. These values are compared with alignment tolerances to determine if any correction is necessary. If suitable tolerances are selected in the tolerance table, the symbols described above indicate if the angle and offset values are within tolerance or not.

角度偏差与位移偏差可以衡量对中情况，并计算是否需要进行调整。如果已经选择合适的公差，测量结果会通过不同颜色表示是否在公差范围之内

The bolt values indicate the movable machine's bolt positions where corrections can be made.

螺栓调整值给出设备对中需要进行的螺栓调整数据



## SHIMMING 垫片调整



The Shimming screen shows bolt values as suitable shim values (0.05 mm / 1 mil).  
垫片视图显示根据垫片厚度所需的调整量

Adjust the angular error by placing shims under the bolts as required  
通过在螺栓下放置垫片调整角度

The arrow show if shims must be added to adjust the machine. 箭头表示需调整垫片

The check sign shows that shimming is not needed. 对勾标志表示无需调整

When shimming is completed, continue to alignment for adjustments of parallel offset.  
调整垫片完成后，继续调整平行偏移



Go to alignment. 进行对中

## ALIGNMENT对中调整



If the angular error has been correctly adjusted in the shimming screen the angular value should now be in tolerance.  
如角度误差已在垫片界面修正，此时应显示公差内。

Now adjust the parallel offset in both directions. The parallel offset is displayed live in the first direction when the sensors are placed in position number 1, and in the second direction when they are placed in position number 2.

现同时调整两个方向的位移偏差，实时显示值随着激光器在位置一、二的变化而改变

Check that both the angular value and the parallel offset are within the required tolerances once the adjustments are completed. 调整过程完成后，再次检查角度与位移偏差是否在所要求的公差范围内。

Alignment is now complete. To confirm the result, re-do the measurement.

对中调整完成后，可重新测量确认



Re-measure.

从新测量

## MACHINE DEFINED DATA

### 自定义设备数据

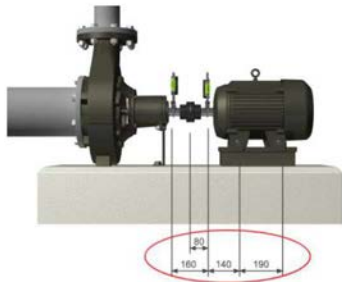
#### INTRODUCTION简介

If the sensors are placed at the same place each time a machine (or more identical machines) is measured, it can be convenient to preload the relevant parameters. The data that can be preloaded are:

如每次激光器都固定在相同位置，则相应的尺寸数据可以预置，测量时直接读取

- The name of the specific machine.  
特定机型命名.
- Distances for the machine, the distance between the sensors (where fixture points are fixed), the distance between the centre of the coupling and the M-sensor, the distance between the M-sensor and the first pair of feet and the distance between the first and the second pairs of feet. 测量所需的各个尺寸

- Target Values as feet values or angle and offset values. 预设的目标补偿值
- Tolerances.公差



#### NOTE! 注意

When using Machine Defined Data, the sensors must always be placed according to the preloaded distances to get correct measurement results.

当使用自定义的设备数据时，激光器必须放置在相同的位置以获得正确测量结果

## STARTING THE PROGRAM.开始程序

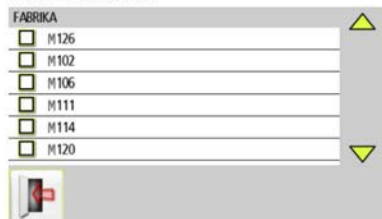


Start the program by touching the Machine Defined Data icon in the Main Menu.

在主界面中点击自定义图标开始程序

## USING MACHINE DEFINED DATA

使用自定义数据



A list of machine types with preloaded data is shown.

之前保存的自定义数据列表

## Select machine.选择

Machines can be selected by touching its machine name. 点击选择设备名称

This starts Shaft Alignment with machine defined data for the selected machine.

## SOFTCHECK™软脚测试

### INTRODUCTION 简介

A soft foot condition needs to be corrected before any alignment takes place. If not, the measurement result will be of no value. It is more or less impossible to establish if there is a soft foot condition without using some kind of measurement tool. The FIXTURLASER Alignment System's built-in Softcheck program checks each foot and displays the result in mm or mils.

在对中调整开始前，应先进行软脚测试，否则对中结果是没有意义的。如果没有使用专业工具，软脚情况通常很难发现。Fixturlaser.对中测量系统内置软脚测试程序可以帮您精确检测软脚情况。

The Softcheck program is entered from the Horizontal Shaft Alignment program.

可以从水平轴对中程序里进入软脚测试程序

## STARTING THE PROGRAM 开始程序



Start the Softcheck by touching its icon in the Shaft Alignment program.

在轴对中程序里选择此按钮

Place the sensors at the 12 o'clock position.  
将激光器置于12.点位置

All the distances must be entered, before checking for soft foot.

Check that all foot bolts are firmly tightened.

开始软地脚测量之前，必须输入激光器间距，M.端激光器与前地脚间距，以及设备前后地脚的间距。检查每个地脚螺栓是否拧紧。

## MEASUREMENT VALUE REGISTRATION 测量



Select a bolt of your choice by touching its icon. 选择你所需要测量的软脚

1. Loosen the bolt fully and wait a few seconds. 完全放松螺栓，然后等待几秒
2. Tighten the bolt firmly, preferably with a dynamometric wrench. 紧固螺栓，最好用扭力扳手紧固
3. Register the measurement value. 记录测量数据



Register the measurement value by touching the confirmation icon.  
点击确认图标记录测量数值



Continue with the rest of the bolts.  
继续其它地脚测量

Re-measurements can be done at any time  
by touching the icon for the requested bolt  
again. 任何时间都可重新测量

## MEASUREMENT RESULT AND CORRECTIONS



Make the necessary corrections and then  
check each foot again (the values show  
approximately how many shims that are  
needed to eliminate the soft foot).  
根据测量结果做调整，然后重新测量。（测量  
结果指导您需要什么垫片以消除软脚）





## TARGET VALUES 目标治预设

### INTRODUCTION 简介

Most machines develop a certain amount of heat while running. In the best case both the driving and the driven machine are affected equally requiring no input of compensation values. But in some applications the driven machine is either hotter, i.e. a pump for hot liquid, or cooler than the driving machine.

大部分设备在运行过程中都会发热，最好的情况是驱动端和被驱动端发热情况一样，无需补偿。不过有些情况下两端的温度并不一致

Machine manufacturers define the thermal expansion of machines differently, but in most cases you will find it as a factor of deliberate misalignment expressed in parallel offset and angular error.

生产厂家会定义每台设备的热膨胀系数，但大多

数情况下只是作为测量结果的平行偏差和角度偏差的来表示的。

In the FIXTURLASER EVO system, you can pre-set target values before starting your

alignment work. Accepted values are feet values and angle and offset values.

系统可以方便您在对中开始之前预设地脚值，角度与位移偏差。

The entered values are target values. Target values mean that these are the values at which the machine should be positioned when not running (cold condition) in order to obtain correct alignment while the machine is running (hot condition).

输入值为目标值。也就是设备在未运行状态下

对中调整，在运行状态下达到正常对中状态。

## STARTING THE PROGRAM 开始程序



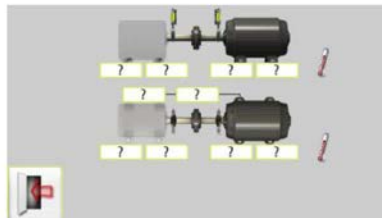
Start the Target Values program by touching its icon in Settings.

在水平转轴对中程序里点选此按钮进入目标预设程序



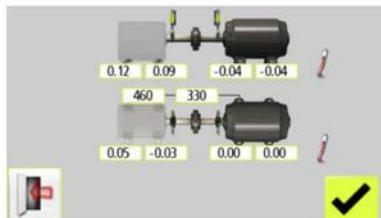
Select one of two ways to express the offset values: Feet values or angle and offset values. 选择任意一种方式输入补偿值：地脚值或角度位移偏差值

## FEET VALUES 地脚值



Touch the feet value boxes. Enter target values for the feet in mm or mils according to the pre-set measurement unit together with the required distances.

点击地脚值按钮，根据预设单位输入目标值（mm.或mils）

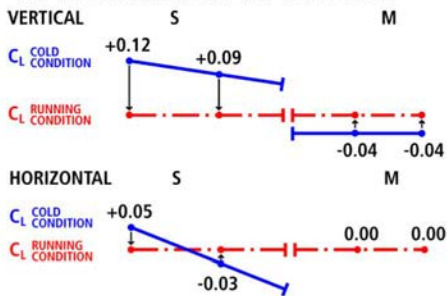


In the example above, the stationary machine will shrink vertically by 0.12 mm at the rear feet and 0.09 mm at front feet while the movable machine will expand 0.04 mm while running.

此例中竖直方向，静止端设备后脚会膨胀0.12.毫米，前脚会膨胀0.09.毫米；可动端设备在运转过程中会下降0.04.毫米。

Horizontally, the rear feet will move 0.05 mm towards you and the front feet will move 0.03 mm away from you while the movable machine does not change its position while running.

水平方向，如可动端设备在运转中不会改变位置，静止端设备后地脚需要向远离测量者方向移动0.05.毫米，前地脚需要向靠近测量者方向移动0.03.毫米。

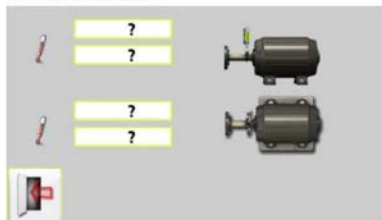


After having entered these feet values, the system calculates how the movable machine should be positioned (target position) in cold condition in order to obtain perfect alignment during running condition.

输入完这些地脚值之后，系统会计算可动端设备在未运转状态需要调整的位置，以达到设备运转之后的完美对中。

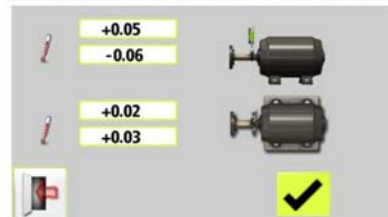
## ANGLE AND OFFSET VALUES

### 角度与位移偏差



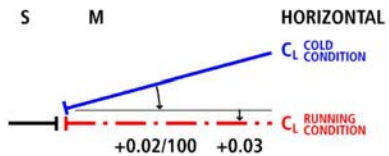
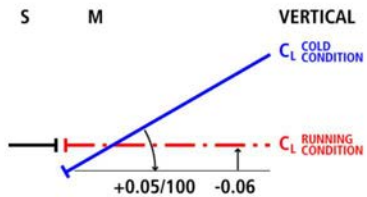
Touch the value boxes and enter target values for the angles in mm/100 mm and target values for the offsets in mm, or mils/inch and mils, according to the pre-set measurement unit.

选择预设按钮输入角度与位移的目标预设值



In the example above, the movable machine should be vertically adjusted to a position with an angular misalignment of  $+0.05$  mm/100 mm and an offset of  $-0.06$  mm.

Horizontally, the movable machine should be positioned with a  $+0.02$  mm/100 mm angular misalignment and a  $+0.03$  mm offset, in cold condition to obtain perfect alignment while running.  
此例中，设备未运转条件下，可动端设备在竖直方向需要调整至角度 $0.05\text{mm}/100\text{mm}$ ，位移 $-0.06\text{mm}$ ；水平方向需调整至角度 $0.02\text{mm}/100\text{mm}$ ，位移 $0.03\text{mm}$ 。在设备正常运转情况下即可达到对中。





## TOLERANCE TABLE公差表

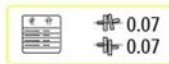
### INTRODUCTION简介

Alignment tolerances depend to a large extent on the rotation speed of the shafts. Machine alignment should be carried out within the manufacturer's tolerances. The table provided in FIXTURLASER EVO can be helpful if no tolerances are specified. The suggested tolerances can be used as a starting point for developing in-house tolerances when the machinery manufacturer's recommended tolerances are not available. The tolerances are the maximum allowed deviation from desired values.

对中的公差取决于轴的转速，结果须达到制造公差内。当没有现成的公差要求时，EVO提供的公差表可根据转速指导公差设定。


It is also possible to enter a customized tolerance. 公差也可自行设定

### OPEN THE TOLERANCE TABLE打开公差表




Open the Tolerance Table by touching this icon in Settings. 在设置界面点击公差图标打开公差表。

	$\text{C}_{\text{rpm}}$	$\pm_{\text{mm}/100}$	$\pm_{\text{mm}}$
<input type="checkbox"/>	0-2000	0.08	0.10
<input checked="" type="checkbox"/>	2000-3000	0.07	0.07
<input type="checkbox"/>	3000-4000	0.06	0.05
<input type="checkbox"/>	4000-6000	0.05	0.03
<input type="checkbox"/>	MY TOL	0.06	0.08



Tolerance Table mm-mode  
公差表：毫米模式

	$\text{C}_{\text{rpm}}$	$\pm \text{mils}/''$	$\pm \text{mils}$
<input type="checkbox"/>	3600	0.5	2.0
<input type="checkbox"/>	1800	0.7	4.0
<input checked="" type="checkbox"/>	1200	1.0	6.0
<input type="checkbox"/>	900	1.5	8.0
<input type="checkbox"/>	MY TOL	0.8	5.0



Tolerance Table inch-mode  
公差表：英寸模式

### SELECT TOLERANCE 选择公差

- Select the tolerance to use in the alignment by touching its check box to the left.

点此框选定所需公差



Confirm. 确认

### CUSTOMIZED TOLERANCES 自定义公差

A customized tolerance can be entered at the last row of the tolerance table.  
可在自定义公差输入所需公差在公差表最后一栏

Enter customized tolerance by touching any of the fields, name/rotation speed to the left and tolerance values to the right  
点击相应的空白区域输入公差，名称等。



## MEMORY MANAGER 存储器管理

### FILE MANAGER 文件管理



#### Open file 打开文件

Touch a file to open it. 点击文件打开它

#### Scroll



Scrolls one page up. 上滚动



Scrolls one page down. 下滚动

#### Select files 选择文件



Touch the check box to the left to select a file.

#### Delete



Deletes selected file.  
删除文件

#### Archive 文件柜



Goes to archive  
(only available when it contains folders with older files).

#### Exit 退出



Exits the Memory Manager.

The Memory has the capacity to store approximately 1200 measurements. When the number of measurements, exceeds 100 measurements in the file manager, a folder with the older files will be automatically created. These folders can then be found in the archive.

存储器大约有1200个测量数据的存储量，当存储器的存储数据超过100个时，旧的文件夹会被自动生成出来，这些文件夹都可以在文件柜中找到。

**NOTE:** When there are a lot of files in the memory, processing can be slow.

注：如存储器文件过多，速度会较慢

## SAVE MEASUREMENT 保存测量结果



### Enter file name 文件命名

Touch the white field to enter a file name.

### Confirm



Confirm.确认

When saving a measurement, both a text file and a picture file (bmp) are created.

当存储一个测量结果，系统会生成一个文本文件与图片文件（bmp.模式）

## TRANSFER FILES TO A PC文件导出至电脑

1. Turn on the display unit and stay in the Main Menu. 打开显示单元，保持在主菜单
2. Attach the display unit to the PC with the USB cable.  
将显示单元通过USB.电缆与电脑连接



3. Touch the connect to PC icon.  
点击图标连接电脑

The display unit will appear as a mass storage device on the PC.  
电脑会将显示单元当成一个大储存器而自动识别

4. The files in the display unit can be transferred to the PC using the ordinary functions in Windows Explorer (i.e. cut, copy or drag and drop).

显示单元中的文件可以通过Windows.操作系统的一般操作实现转移，如剪切，复制，拖拽等。

In the PC there will be two files for each measurement; a picture file (.bmp) and a text file (.txt). The picture file shows the same picture as in the memory. The text file shows just the measurement data.

导出到电脑的每一个测量结果包含两个文件，一个图片文件(.bmp)，一个文本文件(.txt)。图片与显示单元的显示结果一致，文本文件包含测量数据。

It is recommended that you delete the files from the display unit after they have been safely transferred in order to avoid full memory.

在测量结果安全得转移到电脑之后，建议您删除显示单元内的记录，以免显示单元内存过多。

## SHAFT ALIGNMENT HORIZONTAL MACHINES 水平转轴对中

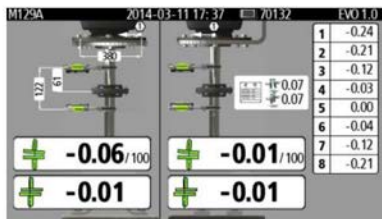


Exit the measurement file.  
退出测量报告

The screen displays measurement results, dimensions, target values if any, file name, date and time, serial number of the display unit, program, program version and tolerances.

屏幕会显示测量结果，尺寸，注释，目标值，文件名，时间，激光序列号，程序版本与公差。

## SHAFT ALIGNMENT VERTICAL MACHINES 垂直转轴对中



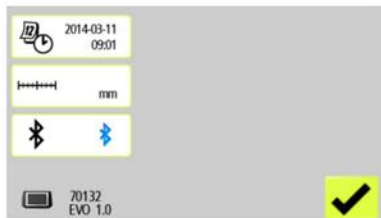
The screen displays measurement results, dimensions, file name, date and time, serial number of the display unit, program, program version and tolerances.

屏幕会显示测量结果，尺寸，注释，目标值，文件名，时间，激光序列号，程序版本与公差。



Exit the measurement file.  
退出测量报告

## GLOBAL SETTINGS 全局设定



The global settings menu includes settings that are universal for all applications. 全局设定菜单包含其它应用的设定。

For most of the settings, the current selection is shown in the icon.

对大部分设定来说，当前设定值均直接显示。

The program version number is also shown on this screen.

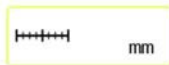
程序版本号同时显示。

### Date and time 时间日期



Opens window for date and time settings. 时间日期设定窗口

### Measurement unit 测量单位



Changes between mm mode and inch mode. 单位有毫米和英寸模式

### Bluetooth settings 蓝牙设置



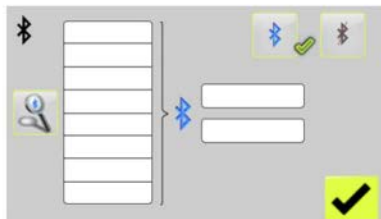
Opens window for bluetooth settings. 蓝牙设置窗口

### Confirm 确认



Exits the Global Settings.

## BLUETOOTH SETTINGS 蓝牙设置



### Communication 连接蓝牙



Activate Bluetooth.  
开启蓝牙



Deactivate Bluetooth.  
关闭蓝牙

### Pairing Bluetooth units .蓝牙单元匹配

Touch the search icon to search for units that are pair able.

点击搜索按钮寻找可匹配蓝牙装置

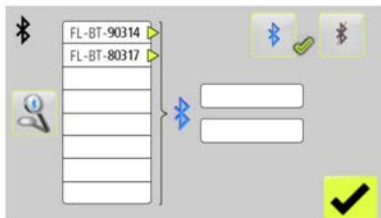


Search for Bluetooth units.

Pair able units will appear in the search list to the left. 可匹配装置会显示在列表左侧

The wireless units must be switched on for the display unit to discover them. The display unit will only discover units approved by FIXTURLASER.  
蓝牙单元必须开启，主机只会发现Fixturlaser提供的蓝牙装置



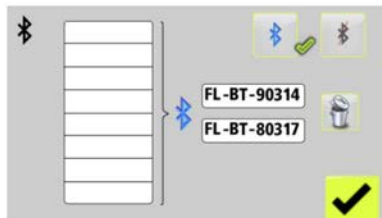


Touch the units to pair in the search list.  
(Maximum two units.)

点击蓝牙单元完成匹配（最多两个）

Paired units will be moved to the boxes  
beside the blue B.

完成匹配的激光单元会进入右侧列表



Units that are paired to the display unit are  
shown in the boxes beside the blue B.

The display unit will only communicate with  
units that are paired and displayed in the  
boxes. 匹配好的蓝牙单元会用蓝色B符号标识  
，主机只会与匹配好的单元进行通信。

If there are units paired to the display unit,  
they have to be unpaired before it is  
possible to pair new units.

如蓝牙单元已经与某主机匹配，则匹配新蓝牙之  
前需要将老的匹配取消

## Unpairing Bluetooth units 取消匹配



Touch the delete icon to unpair units.

点击删除图标取消匹配

## DISPLAY UNIT EVO D 显示主机



1. 5" Touch screen 5寸的触摸屏
2. On button with status LED  
主机电源键及LED显示灯
  - a. Continuously green – ON 绿灯常亮-开机
3. Display Unit battery status 电池电量显示
  - a. Continuously green – connected to charger and battery fully charged 绿灯常亮-电池已经充满电
  - b. Continuously amber – connected to charger and charging 淡黄色-正在充电
  - c. Flashing red - <10% battery capacity 闪红灯-电池电量低于10%
4. USB slave (IP 67) USB接口

## OPERATING MODES

The display unit has two operating modes:  
On and Off. 显示单元有开启和关闭2种工作模式



To turn on the unit, press the  
ON button. 开机键



To turn off the unit, touch the  
Off icon in the main menu. 关机键

In case the system fails to respond, it is possible to turn it off by pressing down the ON button for more than 15 seconds. 如图标没有反应，也可以长按电源键15秒关闭显示单元

## CONNECTIONS.连接

The main connection for the Display Unit is the built in Bluetooth connection. See chapter “Global settings” for instructions on how to pair measurement units. 显示单元的主要通信连接通过蓝牙，参见“全局设定”匹配蓝牙单元

The USB slave connector is used to charge the battery and for attaching the Display Unit to a PC to transfer measurement data. When attached to a PC the unit will act as a Mass Storage Device.

USB接头可用于充电和连接电脑传输文件，当连接电脑时主机会启动存储管理器连接驱动。

## POWER SUPPLY

The FIXTURLASER EVO is powered by a high-capacity rechargeable Li-Ion battery in the display unit, or by the external power unit. Fixturlaser.EVO使用高性能可充电锂电池，或连接外部电源

The operating time of the batteries is approximately 8 hours when the system is used for a typical alignment work.

电池可以持续工作8当系统进行对中工作时

If the system turns off due to low power, the resume function will save the data.

When the system is turned on again after battery recharge or connection of external power, you will be prompted to choose whether to return to the state when the unit was turned off (i.e. resuming operation without loss of data) or start the main menu.

显示单元因电量过低关闭时，恢复功能会保存当前数据，重新充电或连接外部电源，开启之后可选

择是否回复到之前测量或重新进入主菜单。

The external power unit is connected to the USB mini connector on the display unit and to a wall socket with 110 - 240 Volts.  
外部电源工作电压110-240伏

When the external power supply is connected, the unit will automatically start charging the batteries. This will be indicated by the battery status LED. The charging time is approximately 8 hours for fully drained batteries. The charging time will be longer if the unit is turned on while being charged.

连接外部电源时，系统自动充电，电池LED指示灯会显示电池状态。完全充满需要大约5-6小时。如充电时显示单元处于开启状态，充满时间会延长。

When used in typical conditions the batteries will sustain good capacity for approximately 2-3 years before needing replacement. Contact your sales representative for battery re-placement. 典型的使用状况下电池可使用2-3年，如需更换电池请联络当地经销商。

The batteries contain safety circuitry to operate safely with the display unit. The unit can therefore only be used with the Li-Ion batteries supplied by FIXTURLASER.

Improper replacement of batteries can cause damage and risk for personal injury. Please refer to the chapter on safety for further instructions.

电池包含安全电路，请勿使用非Fixturlaser提供的电池。不当的电池更换可能导致人身伤害。

### **BACKLIGHT** 背光

If no icon is pressed within 30 minutes the backlight will dim automatically.

Press anywhere on the screen to turn the backlight on again. 主机待机30分钟背光会变暗，触摸屏幕后背光将变亮。

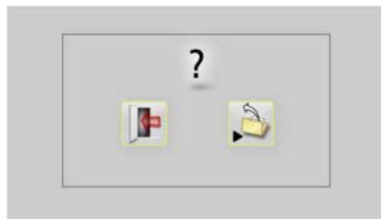
### **AUTO-OFF**

If no icon is pressed within 60 minutes the system will turn off automatically.

主机待机60分钟将自动关机

### **RESUME FUNCTION** .恢复功能

If the system is turned off due to low power, the resume function will save the data. 如因电量过低关机，系统会自动保存当前数据。



When the system is turned on again after charging the batteries, you will be prompted to choose whether to return to the stage when the system was turned off (i.e. resuming operation without loss of data) or start the Main Menu. 充电后系统重新开启，可以选择继续刚才的测量或重新进入主菜单（恢复测量的数据已保存）。

## UPGRADING THE SOFTWARE 软件升级

Any upgrades of the software will be distributed or made available for download on our website.

新的升级软件会发布或置于网页上方便下载

1. Turn on the display unit and stay in the Main Menu. 打开显示单元，保持在主菜单
2. Attach the display unit to the PC with the USB cable.

将显示单元通过USB.电缆连接到电脑



3. Touch the connect to PC icon.  
点击连接电脑图标

The display unit will appear as a mass storage device on the PC.  
系统会自动识别显示单元。

4. Copy the file containing the new software to the display unit.  
将新软件复制到显示单元

NOTE: A zipped file must be unzipped before copying it to the display unit.

注意：安装包必须在未解压的情况下复制到显示单元

5. Disconnect the display unit from the PC and wait until the display unit turns itself off (this can take several minutes).  
等待显示单元自动关闭（需要花费几分钟），然后断开连接。
6. Turn on the display unit. The upgrade file will be automatically detected and installed. This can take approximately one minute. Wait until the Main Menu is displayed, and the DU is then ready to be used again. 打开显示单元，系统会自动识别升级文件并安装，等待大约一分钟后，主菜单显示，系统可以重新使用。
7. Settings and stored measurements will not be affected by an upgrade.  
升级不会影响测量的设定与结果保存。

## CALIBRATING THE TOUCH SCREEN 屏幕校准

In order to make the touch screen to respond to the icons on the display, it may be necessary to recalibrate it from time to time. 为保持触摸屏的准确性，需要经常校准屏幕

Screen calibration procedure: 校准步骤如下：

- Start the system. 开启系统
- Wait until the main menu appears. 直到主界面出现
- Press down on the screen somewhere outside of the icons for 10 seconds. 在空白区域长按屏幕10秒
- The screen calibration function should start. 屏幕校准程序启动

- Touch and hold down on the target displayed until it moves. 点击目标位置直到下一个点
- Repeat the step above on the 4 new positions of the target. 重复4个位置



### NOTE!

For best results please use a stylus for calibration.  
为获得最佳的校准效果，请使用尖利物



## SENSORS M3 AND S3

### M3和S3激光探测器



1. ON/OFF button with status indication LED 电源键及LED指示灯
  - a. Continuously green – On持续绿灯-开启
  - b. Switching green/red – Gyro activated.红绿闪烁-陀螺仪启动
2. Mini USB for charging USB充电接口
3. Laser transmission indication LED 激光指示灯
  - a. Green – laser transmission 绿色-激光发射
4. Bluetooth indication LED 蓝牙指示灯
  - a. Continuously blue – paired and ready. 持续蓝光-蓝牙已连接
  - b. Flashing blue – searching/ready to pair 闪烁蓝光-蓝牙搜索中或未连接
  - c. No light – Bluetooth disabled. 无蓝光-蓝牙未开启



5. Battery status button – press to instantly show the battery status (also works when the unit is switched off).  
 电池状态按钮—显示当前电量（即使激光单元处于关闭状态）

6. Battery status LED. 电池状态指示灯
- One LED continuously red – less 10% charge left.  
 一个红灯持续亮—电量小于10%
  - One LED flashing red – less than 5% charge left.  
 一个红灯闪烁—少于5%电量
  - One LED continuously orange – charging  
 一个橙灯长亮—充电中
  - One LED continuously green – fully charged.  
 一个绿灯持续亮—充满
7. Battery status LED when battery button is pressed  
 按下电池状态按钮
- Continuously green – battery status  
 绿灯长亮—电池电量显示
  - Rolling green – battery charging  
 滚动绿色—充电中

## **OPERATING MODES**工作模式

M3 and S3 units has two operating modes:  
On and Off. 开启与关闭

Turn the units on and off by pressing the  
ON/OFF button firmly. 按开关键开启与关闭激光器

In case the units fail to respond, it is possible  
to turn it off by pressing down the ON  
button for more than 10 seconds.  
如正常关闭没有反应，长按10秒可以关闭

## **CONNECTIONS** 通讯连接

### **Bluetooth connection**蓝牙连接

The main connection for M3 and S3 units is  
the built in Bluetooth connection. The units  
will automatically connect to the display unit  
when turned on as long as they are paired.  
See chapter “Global settings” for  
instructions on how to pair measurement  
units to the display unit.

激光单元的主要通信通过蓝牙，参见  
“全局设定” 匹配蓝牙单元

To avoid accidental Bluetooth transmission  
in a restricted area the Bluetooth function  
can be completely disabled – contact your  
local sales representative for more  
information.

为避免在受限区域使用蓝牙传输，蓝牙功能应完  
全关闭，请联络当地经销商

If the Bluetooth has been disabled (as  
indicated by the fact that the Bluetooth LED  
is not flashing or continuously blue when the  
unit is turned on) it can be enabled by  
pressing the battery status button quickly 5  
times in a row.

如蓝牙未激活（蓝牙指示灯无任何闪烁），快速  
按电池状态按钮5次可激活蓝牙。

## POWER SUPPLY电源

The M3 and S3 units are powered by a high-capacity rechargeable Li-Ion cell, or by the external power unit.

M3,S3激光单元使用高性能可充电锂电池，或连接外部电源

The operating time of the batteries is approximately 17 hours when the system is used for a typical alignment work (continuously on).

电池可连续使用17小时

The M3 and S3 units can be charged with the supplied combined charger or any 5V USB charger or battery life extender.

可使用组合的充电器通过5V.USB接口充电

When the external power supply is connected, the unit will automatically start charging the batteries. This will be indicated by the first battery status LED turning orange, when the unit is fully charged the LED will turn green. By pressing the battery status button the exact charging status can be monitored.

当外部电源连接后，激光单元自动开始充电。电量指示灯第一个会变成橙色。完全充满后会变成绿色。按下电量状态按钮可监控电池状况。

The charging time is approximately 8 hours for fully drained batteries. The charging time will be longer if the unit is turned on while being charged.

完全充满需要8个小时，如激光单元开启，充满时间更长。

When used in typical conditions the batteries will sustain good capacity for approximately 2-3 years before needing replacement. Contact your sales representative for battery re-placement. 典型的使用状况下电池可使用2-3年，如需更换电池请联络当地经销商。

The batteries contain safety circuitry to operate safely with the unit. The unit can therefore only be used with the Li-Ion batteries supplied by FIXTURLASER. Improper replacement of batteries can cause damage and risk for personal injury.

Please refer to the chapter on safety for further instructions.

电池包含安全电路，请勿使用非Fixturlaser提供的电池。不当的电池更换可能导致人身伤害。





**FixturLaser**

Brand of ACOEM

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**[www.fixturlaser.com](http://www.fixturlaser.com)**

**飞翔中国有限公司**

广州市天河区天河路625号天娱广场东塔  
9楼903 (510630)

Tel: (020) 8526 2155

Fax: (020) 8526 1105

[www.fixturlaser.cn](http://www.fixturlaser.cn)